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Wireless Sensor Networks (WSNs)

Benefits:

- · Fine-grained sensing
- Easy deployment, no infrastructure required
- Enable new class of applications uQuery Engine

Challenges:

- · Resource constraints (memory, bandwidth, energy)
- · Large-scale coordination
- · Combine the problems of networking, signal processing, real-time and embedded computing

Requirements for uQuery Engines

- Targeted at end-users, not programmers
- Dynamic: deploy and change behavior at run-time
- · Support concurrency inherent to ambient systems
- · Multiplicity of end-users

How can we program this system? Adapted from: [Boulis, 2005]

WSN Programming

State of the Art

- Programming tools focused on efficiency
- Low-level, C-based programming language (nesC)
- Lightweight, component-based OS (TinyOS)
 - Supports real-time programming, sensing, concurrency
 - · Applications are compiled together with the OS

Macroprogramming WSNs

- Regiment, Semantic Streams, spreadsheet programming
- · Do not meet requirements for uQuery Engines



Connecting together a large number of small computers with sensing and actuating capabilities, to collectively and costeffectively solve problems, based on real-time data.

Application Example: Break Beam Detector

We want to detect an object passing through a break beam sensor, on request:

- · Wait for a request message from the user
- · Perform the requested action
 - Execute detectBeamEvent() primitive
 - · Keep checking the sensor until a change in status is detected
- Send the result of detection back to the user



Mica2-Dot and Telos motes The user (programmer) is responsible for choosing the right OS and

network components, and assembling them along with the specific application logic into an executable program.

```
/* Detect break beam event application (code excerpt) */
configuration Example {}
implementation {
       // list of application components
       components Main, ExampleM, LedsC, GenericComm, TimerC,
    Photo, CC1000ControlM;
      // statically link all components
Main.StdControl -> GenericComm;
Main.StdControl -> TimerC;
Main.StdControl -> Photo;
       Main.StdControl -> ExampleM;
ExampleM.SendMsg -> GenericComm.SendMsg[10];
       ExampleM.ReceiveMsg -> GenericComm.ReceiveMsg[10];
ExampleM.CC1000Control -> CC1000ControlM;
       ExampleM.Timer -> TimerC.Timer[unique("Timer")];
ExampleM.Leds -> LedsC;
       ExampleM.PADC-> Photo;
module ExampleM {
implementation {
       TOS_Msg msgbuf;
       uint8_t msglen, sendPending;
volatile uint8_t ioPending;
       uint16_t ioData;
       // primitive function #20: detect beam event (using photo sensor,
       uint16_t detectBeamEvent();
       // I/O: convert split phase non-blocking I/O to blocking I/O
       uint16_t IO(uint16_t a, uint16_t b) __attribute__((C,spontaneous)) {
   while (ioPending) yield();
   if (a == 20) { call PADC.getData(); ioPending=1; }
              while (ioPending) yield();
              return ioData;
       async event result_t PADC.dataReady(uint16_t data) {
              ioPending=0; ioData=data;
              return SUCCESS;
```

Note the following issues with the code below.

- - Specification and linking of components at compile time
- · All components are compiled into a single image deployed on the sensor
- Low-level:
 - · Programmer is responsible for managing: timing, communication, memory management, error handling
- No separation of concerns:
 - OS and network programming elements are inextricably linked with business logic programming elements

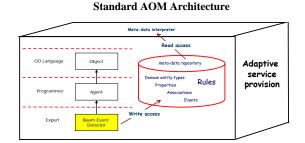
```
// Communication: receive requests for execution and send results
void sendPacket(uint8_t *buf, uint8_t n)
__attribute__((C,spontaneous)) {
     memcpy(msgbuf.data, buf, n);
     msglen = n;
     if (call SendMsg.send(TOS_BCAST_ADDR, msglen, &msgbuf)
      == SUCCESS)
          sendPending = 1;
uint8_t isSendPending() __attribute__((C,spontaneous)) {
     return sendPending;
event result_t SendMsg.sendDone(TOS_MsgPtr mp, result_t success) {
     if (!success) call Timer.start(TIMER_ONE_SHOT, 200);
     else {
          call Leds.redToggle(); sendPending = 0;
     return SUCCESS;
event TOS_MsgPtr ReceiveMsg.receive(TOS_MsgPtr mp) {
     TOS_Msg m;
     call Leds.greenToggle();
     if ((uint8_t)mp->data[0] == 20)
          m.data = deref(detectShadow());
          sendPacket((uint8_t *)m.data, strlen(m.data));
event result t Timer.fired()
     return call SendMsg.send(TOS_BCAST_ADDR, msglen, &msgbuf);
// Implementation of detectBeamEvent primitive
uint16_t detectBeamEvent() {
   int i;
     uint16_t data, avg = 0;
     ledSet(0);
     for (i = 0; i < 10; i++)
          avg += IO(2, 0);
     avg /= 10;
     while ((data = IO(2, 0)) > avg - 15) yield();
     ledSet(7);
     return list(2, newWord(20), newWord(data));
```

Ambiance: Adaptive Object Model-based Platform for Macroprogramming Sensor Networks

AOM is a meta-data interpreter

Meta-data corresponds to data that specifies the Programs':

- Object-model (Structure and Behavior)
- Windows, Menus, Configuration Panel, ...
- · Saved as configuration data



Open Issues with AOMs

- Have not been applied to WSNs
- · Lack of standard techniques for
- WSN dynamic code generation
 - · Supporting concurrency
 - · Supporting separation of high-level control from the execution
- · Run-time optimization

Extended AOM Architecture for Macroprogramming WSNs

Knowledge level

- Comprises:
 - · Conceptual ontology
 - · Behavioral ontology
 - Framework for specifying queries as a composition of services through mediation of concepts
- · Assumptions:
 - · Completeness of the service ontology
 - · Acknowledgeability of the users in the domain covered by the ontologies
 - · Low-level data, such as the sensor id, may be provided by users (in the process of being relaxed)
- Keeps track of static and dynamic metadata.

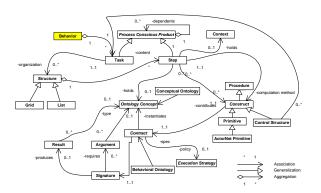
Knowledge leve Adapt Active object Intercession Passive object Operational leve Dynamically-composed

Operational level

- Comprises a set of mobile agents
- The agents:
 - · Are defined dynamically
 - · Execute concurrently
 - · within the WSN, and
- on a single node · Based on a formal model of computation
 - In order to be verifiable
 - Actors

Query Interpretation and Execution

Dart: Query Representation Framework



The Core Design of Dart: A Reusable and Extendible (Global) Behavior Representation Framework

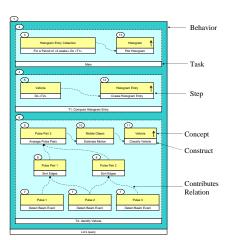
Structure of queries

- · Finite directed acyclic graph
- Recursive
- · Steps may hierarchically point to tasks
- Reflective
 - · Same set of concepts reused to extend the system

Semantics of queries

- · Parallel evaluation of contributions
- Limited to their dependencies
- · Different execution semantics
- · Same set of concepts reused to extend the system
- value binding
- · method binding

Query Representation Example



Liz's Query: compute histogram of vehicle arrival times for a period of two weeks Source: [Whitehouse, Liu, Zhao 2006]

Collaborators:





Noury Bouraqadi Computer Science Research Team. Ecole des Mines de Douai







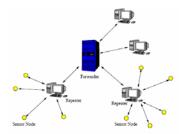
Vincent Ginot Mobidyc Project French National Institute for Agricultural Research



ActorNet: Implementation of the Operational Level

At the operational level, queries are executed by ActorNet

- · A system of mobile, concurrently executing agents called actors
- · Actor code is dynamically generated by the meta-level
- ActorNet language is extended with new keywords and services providing the means to link the meta-level and the operational level of the Ambiance platform



ActorNet platforms are deployed on sensor nodes or PCs

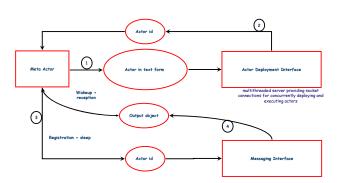
 Provide resource management, scheduling, communication, migration, sensing and actuation, etc., for actors.

Break Beam Detector Example

For the break beam detector, the meta-level will generate the code for an actor of the Detect Beam step.

- An ActorNet agent template is provided by the execution strategy
- The Detect Beam meta-actor computes and fills in:
 - the destination sensor id (for migration)
 - meta-actor id (for communication)
 - the primitive to be executed (for application-specific functionality)
 - the arguments to the primitive (for control)

Primitive Processing Algorithm



ActorNet Agent code for a call to the Detect Beam Primitive

How does Ambiance satisfy the requirements of uQuery Engines?

The Ambiance platform supports:

- · Using a WSN to serve concurrent users
- Dynamic, end-user-driven service specification
- Complex queries, comprising sensing and actuation

While meeting WSN constraints:

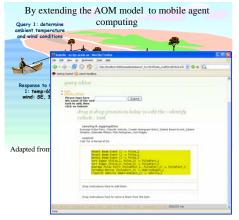
- Embedded, concurrent, distributed computing
- On highly resource-limited hardware components
- · Work with a dynamic set of sensing resources

The two-level approach to architecting uQuery Engines allows separating:

- query representation and reasoning concerns, from
- those of their effective execution on divers runtime platforms
- through model-to-code transformation.

Using a mobile agent system as the query execution environment provides:

- dynamicity and concurrency of macroprogramming, while enabling
- load balancing and other optimizations required by the WSN environment



Web-based uQuery Engine User Interface

Uses: Seaside framework (http://www.seaside.st/) and Squeak (http://www.squeak.org/)

Separation of business logic primitives from the core of the mobile agent system, facilitates addition of new domain-specific primitives

Hooks are provided for quality attributes, such as:

- Security: automated supervision for security checks
- · Auditability: who has been involved in what
- Non-repudiability: who has initiated which action

Reusability and extendibility of:

- The Ambiance Platform
- Its query representation framework